Metadata form of Silva Fennica

This form is designed for writing the elements of metadata, which are used in the description of research materials such as data and codes. The form is based on the work done in the Work Group "Description of research materials" under the Finnish Open Science Coordination.

Item	Description	Responsible
Name of the data / code	Comparison of manual and automated coverage path planning for mechanized forest regeneration	Author
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Owner of the material		Author
Publisher	Silva Fennica, and the authors	Author
Funder	This research was partly conducted within Trees For Me, a center of excellence supported by the Swedish Energy Agency [P2021-90272] and almost 50 stakeholders. In addition, this work was supported by AutoPlant, which was funded by the Swedish Innovation Agency, VINNOVA [2023-02747]. Finally, sincere gratitude is expressed to Holmen Skog for providing the PlantMax and hpr data.	Author
Description	Article and figures	Author
Methods	-	Author
Variables	-	Author
Author keywords	Routing, Precision Forestry, Planting, Site preparation, Automation, Mechanization	Author
Vocabulary keywords (community standard)	-	Author
Discipline	Forest Engineering, Forest vehicle systems, Precision Forestry	Archive/Repository/Publisher
Type of material	Article and digures	Author
Language	Eng, swe	Author
Time range covered	YYYY-MM-DD	Author
Geographic region	SE	Author
Version	-	Author
File format(s)	.docx, .png, .jpg, .shp	Author
Availability of the materials (open, embargo, registration,	The map information can mostly be found in the GitHub repository https://github.com/LTU-Machine-Design/CPP_comparison_mechanized_forest_regeneration	Author

limited, registration required)	DEM and DTW maps are licenced, and is available at these authorities https://www.lantmateriet.se/sv/geodata/vara-produkter/produktlista/ https://www.skogsstyrelsen.se/e-tjanster-och-kartor/karttjanster/geodatatjanster/rest/ The coverage path planners are not commercial software, but it is possible to set up a similar model by following the steps and equations in this, and the previous papers.	
Justification for access restrictions	Licenced maps for input data. The source code for the two coverage path planners are not available due to intellectual property, but it is possible to set up a similar model by following the steps and equations in this, and the previous papers.	Author
Licence	CC BY-SA 4.0	Author
Connections with other research materials	HasPart, the CPP are further development from https://doi.org/10.1007/s11676-025-01834-x And https://doi.org/10.1080/14942119.2025.2469201 But this paper and the dataset is standalone and has not any connections with previous works.	Author
Access to the connected research materials	Both previous coverage path planners are published open access at https://doi.org/10.1007/s11676-025-01834-x https://doi.org/10.1080/14942119.2025.2469201	Author
Codes only: hardware/software requirements for running the code	https://github.com/LTU-Machine-Design/CPP_comparison_mechanized_forest_regeneration Both TerraTrail and Pathfinder are not commercial software. Both are just algorithms that are developed within a research project. The codes of both coverage path planners is not open source, but it is possible to set up a similar model by following the steps and equations in this, and the previous papers.	Author
Connections to other products of research	https://doi.org/10.1007/s11676-025-01834-x https://doi.org/10.1080/14942119.2025.2469201 https://doi.org/10.3390/f15020263	Author
Personal data	None	Author
Confidential or secret data	The source code is not available, but it is possible to set up a similar model by following the steps and equations in this, and the previous papers.	Author
Publication date	GitHub: 2025-05-16	Archive/Repository/Publisher
Preservation policy	The data is published on GitHub until further notice.	Author
Permanent identifier (PID)	-	Archive/Repository/Publisher